

Stability and Control of Resistive Wall Modes in Low-Rotation Tokamak Plasmas

EX/7-1Ra: Active Control of Resistive Wall Modes in High Beta Low Rotation Plasmas

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EX/7-1Rb: Plasma Rotation and Wall Effects on Resistive Wall Mode in JT-60U

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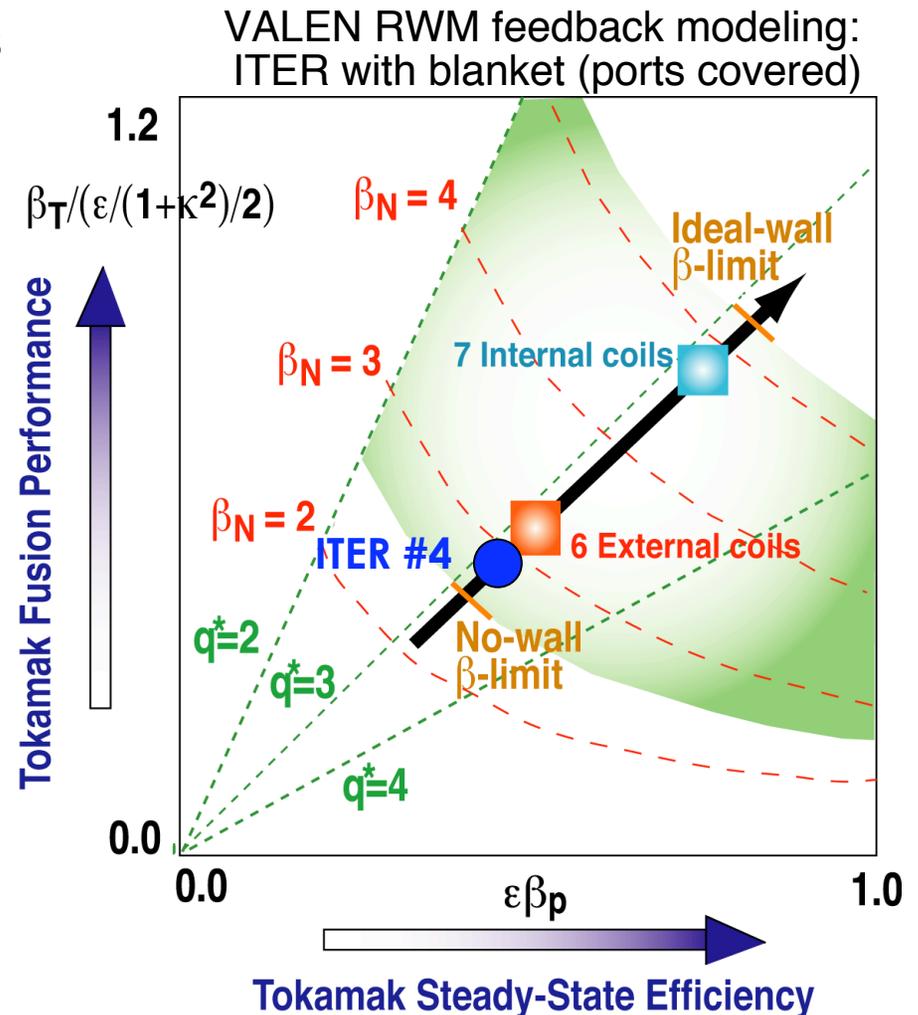
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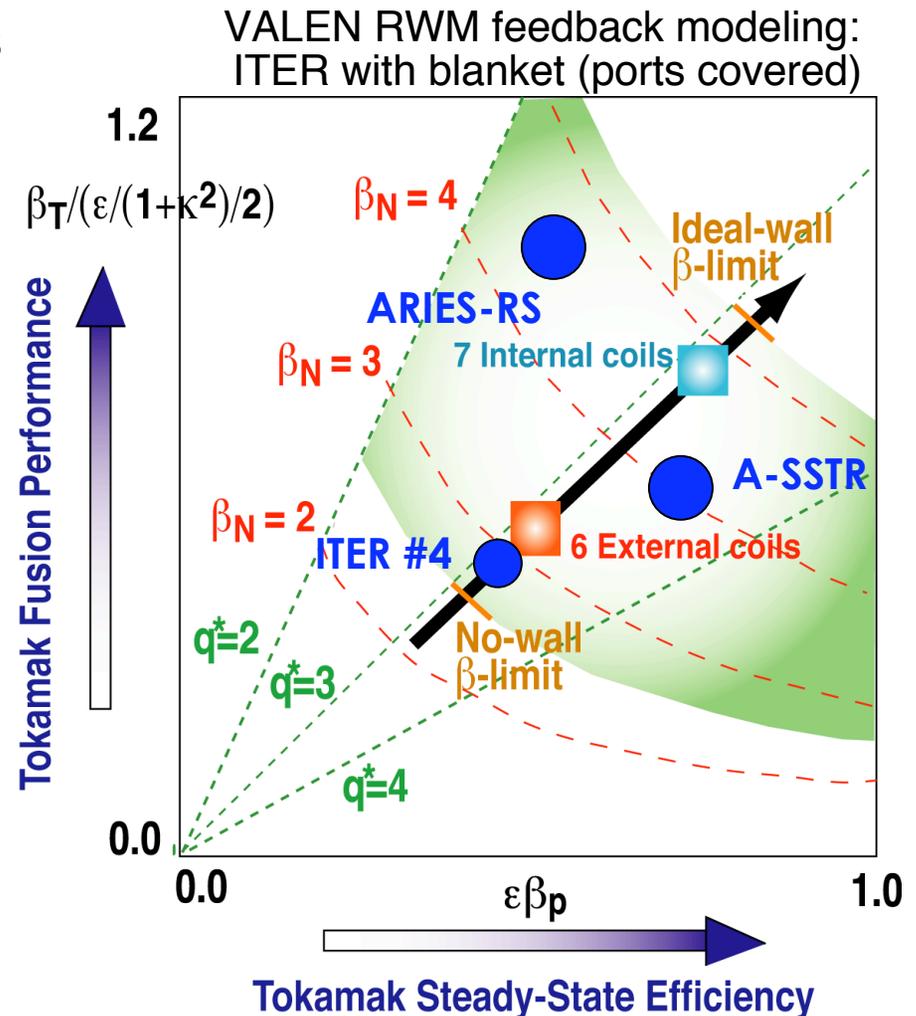
Resistive Wall Mode Stabilization is Needed for Steady State Tokamak Operation at High Fusion Performance

- ITER Steady-State scenario (#4) requires Resistive Wall Mode stabilization
 - Target: $\beta_N \sim 3$, above the no-wall stability limit $\beta_N^{\text{no-wall}} \sim 2.5$
- Sufficient plasma rotation could stabilize RWM up to ideal-wall β_N limit
- Present ITER design of external error field correction coils is predicted to allow RWM feedback stabilization if plasma rotation is not sufficient

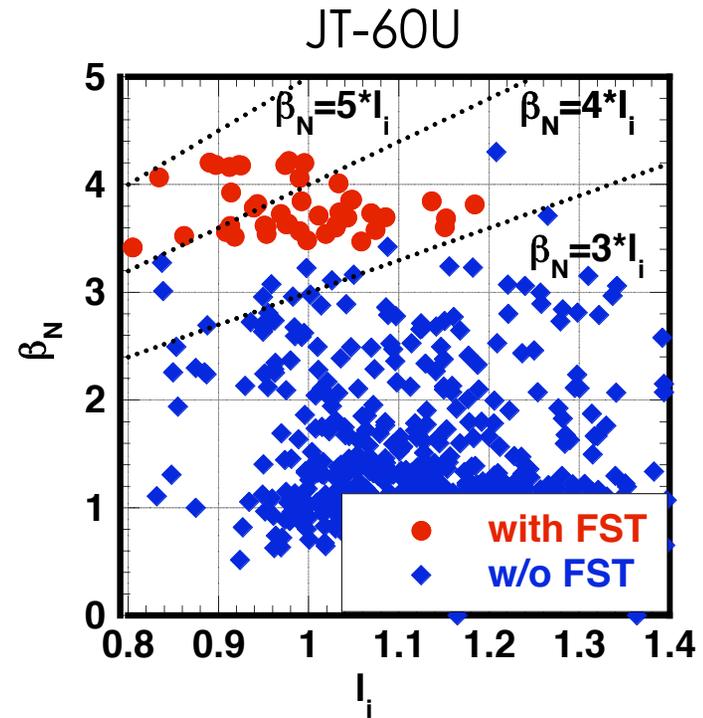
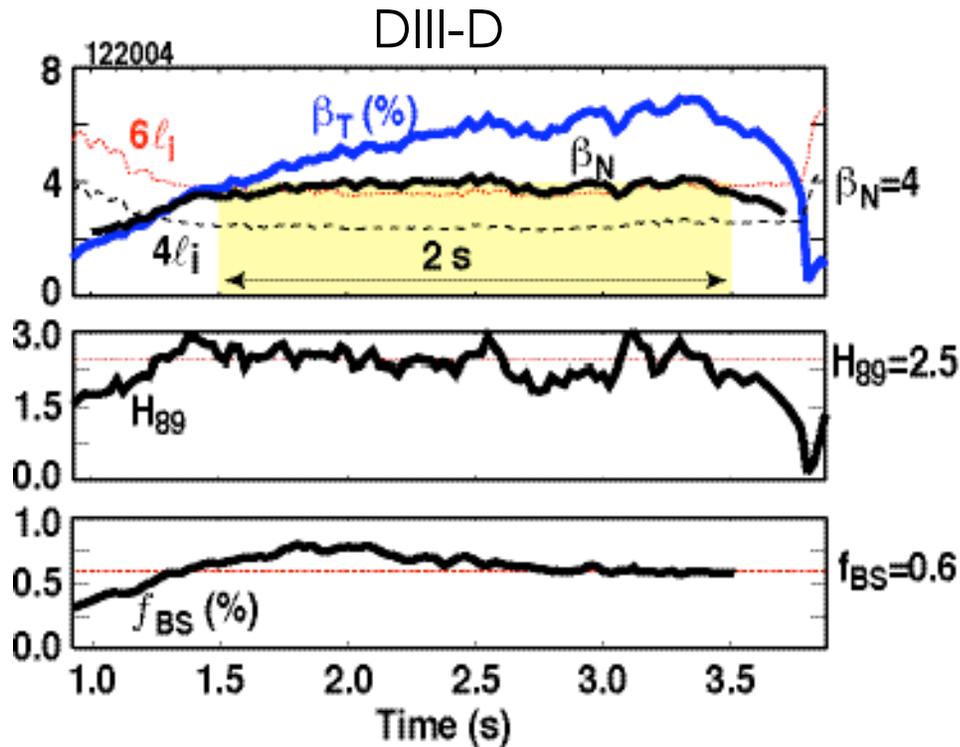


Resistive Wall Mode Stabilization is Needed for Steady State Tokamak Operation at High Fusion Performance

- **ITER Steady-State scenario (#4) requires Resistive Wall Mode stabilization**
 - Target: $\beta_N \sim 3$, above the no-wall stability limit $\beta_N^{\text{no-wall}} \sim 2.5$
- **Sufficient plasma rotation could stabilize RWM up to ideal-wall β_N limit**
- **Present ITER design of external error field correction coils is predicted to allow RWM feedback stabilization if plasma rotation is not sufficient**
- **Improved design for RWM stabilization could allow studies of scenarios approaching advanced tokamak reactor concepts, i.e. $\beta_N > 4$**



RWM Stabilization by Rotation Allows Demonstration of High Performance Tokamak Regimes

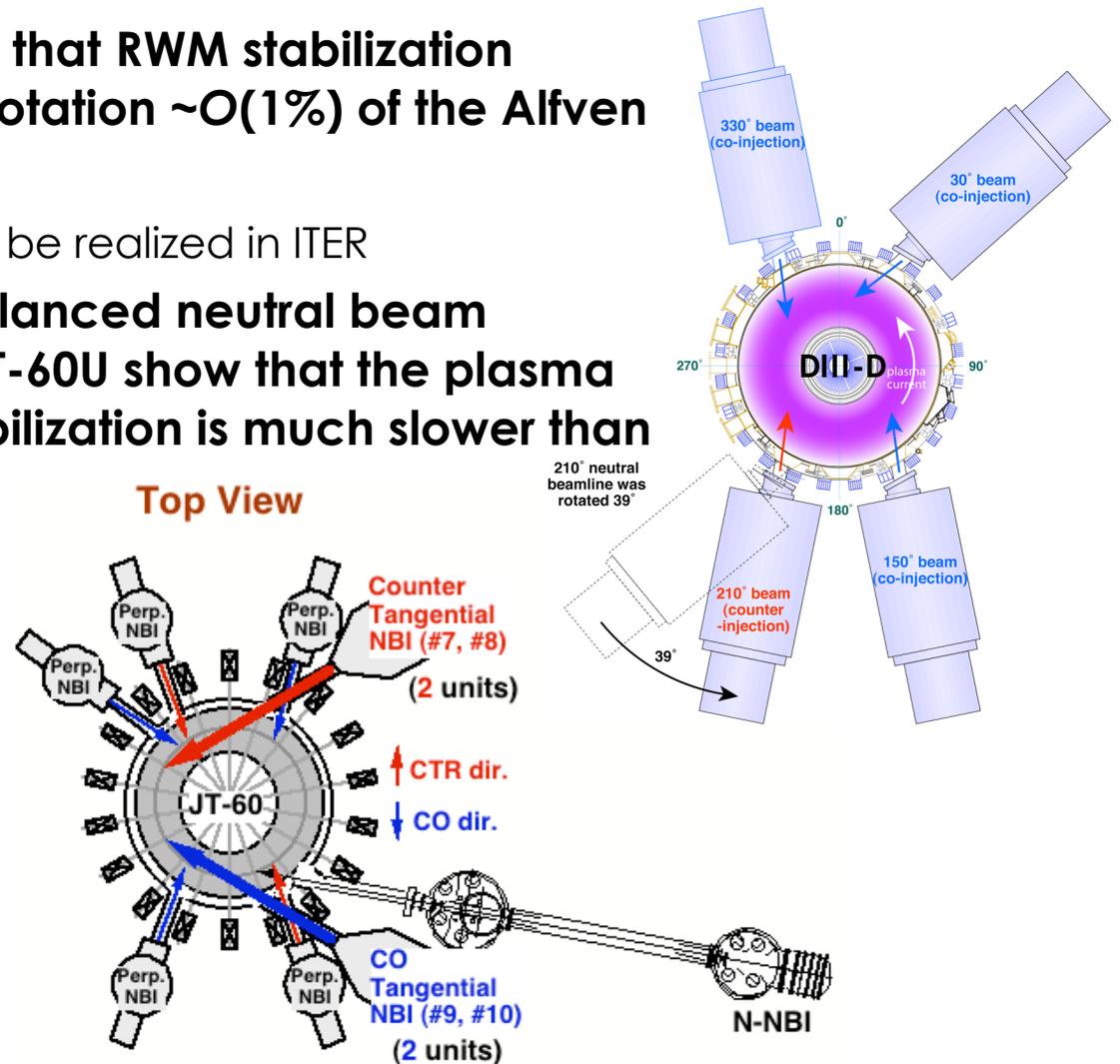


- High β , β_N , high bootstrap current fraction, high energy confinement sustained simultaneously in DIII-D
 - RWM feedback -> sustained high plasma rotation

- High β_N achieved with ferritic steel tiles in JT60U
 - Reduced ripple loss -> higher confinement and rotation with smaller plasma-wall separation

Will RWM Stabilization by Rotation Work in ITER?

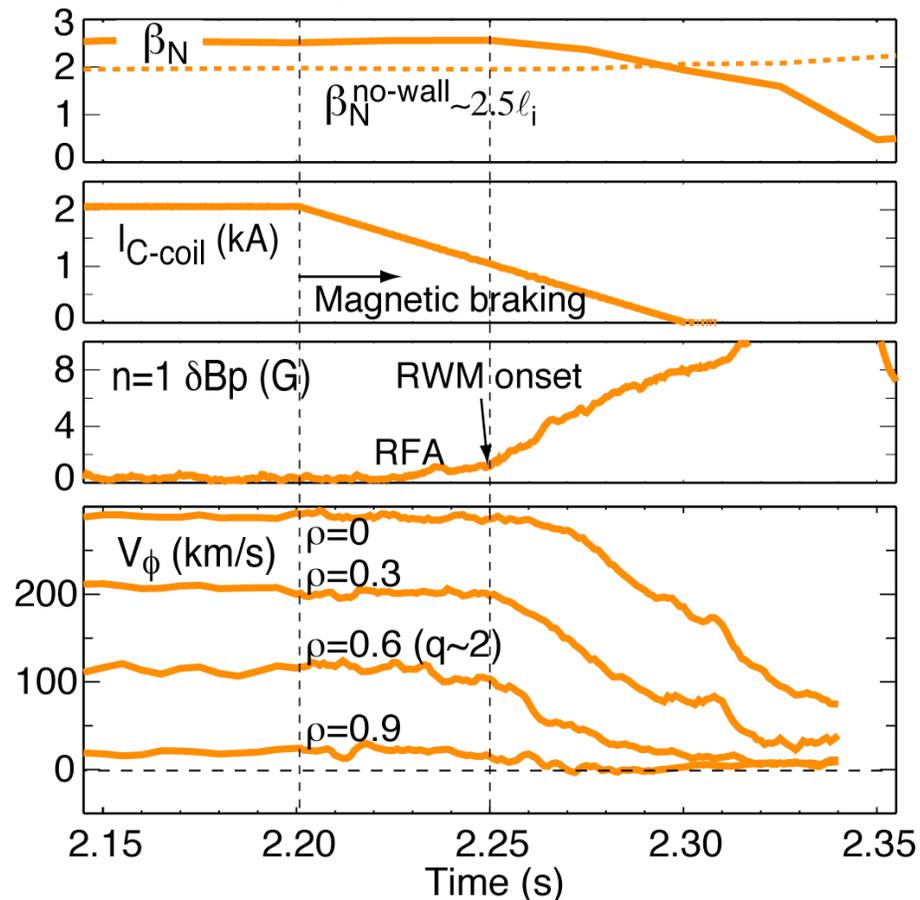
- Until recently, it was believed that RWM stabilization required mid-radius plasma rotation $\sim O(1\%)$ of the Alfvén frequency, Ω_A
 - This level of rotation may not be realized in ITER
- Recent experiments using balanced neutral beam injection (NBI) in DIII-D and JT-60U show that the plasma rotation needed for RWM stabilization is much slower than previously thought
 - $\sim O(0.1\%)$ of Ω_A
 - Such a low rotation should be easily achieved in ITER
- Even with sufficient rotation, active feedback may still be needed, but the system requirements could be reduced



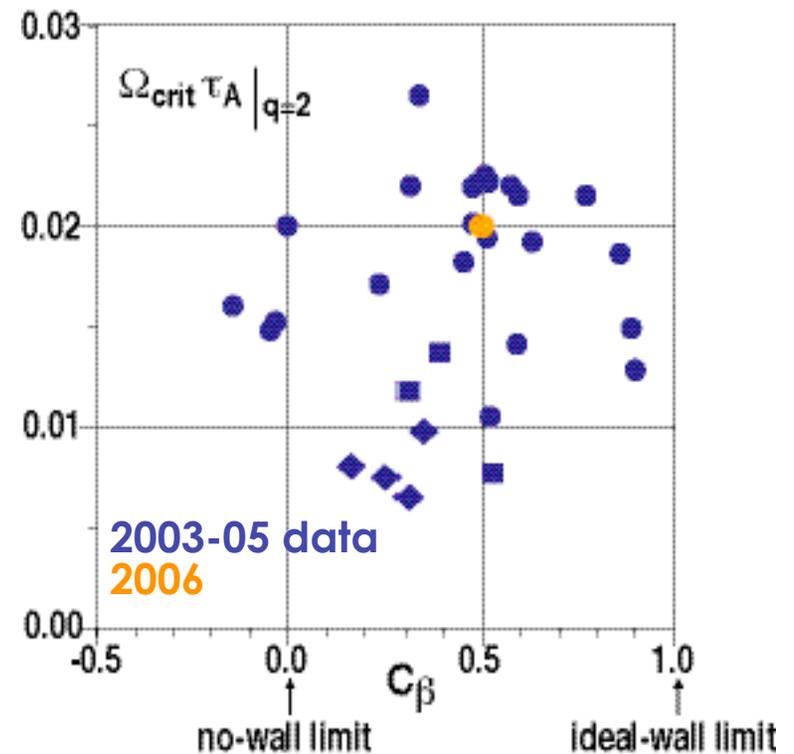
Previously, RWM Rotation Thresholds Were Measured Through Magnetic Braking by n=1 External or Intrinsic Fields

- **DIII-D using only uni-directional NBI:**

- Magnetic braking is applied by removing the empirical correction of the intrinsic n=1 error field

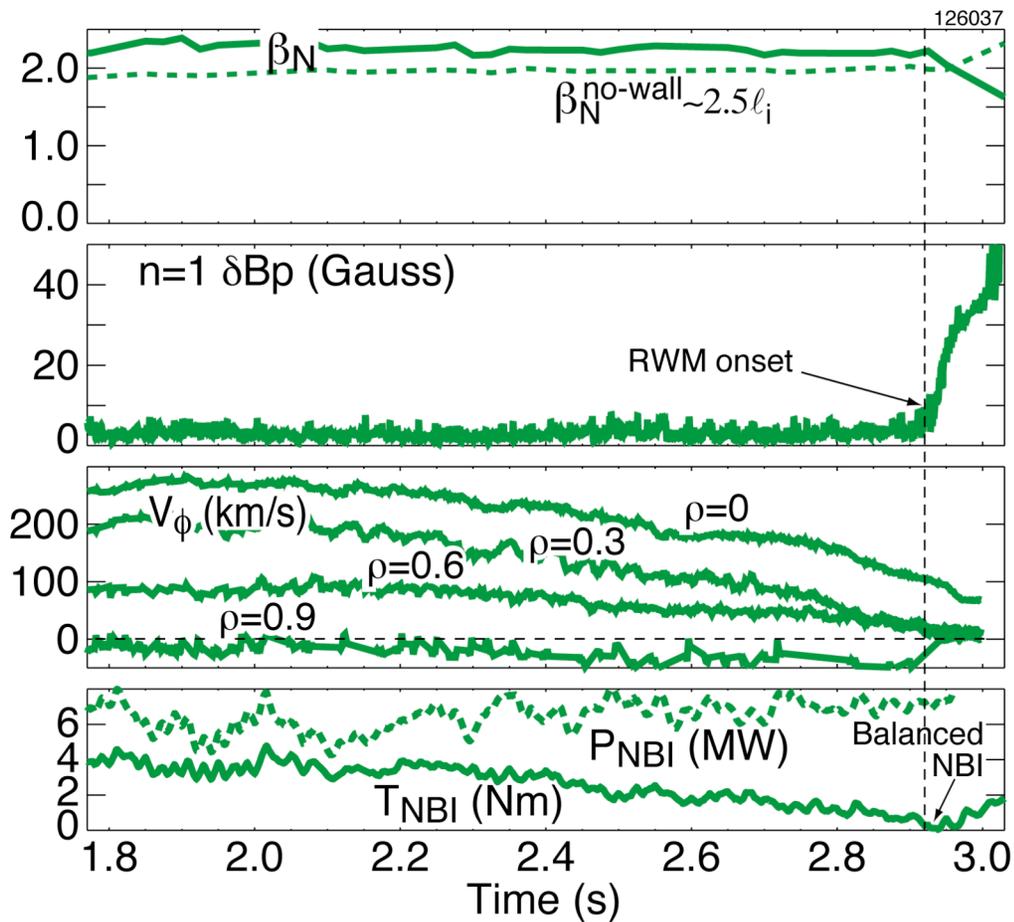


- Critical rotation frequency Ω_{crit} at $q = 2$ surface ranges from 0.7 to 2.5% of local Ω_A

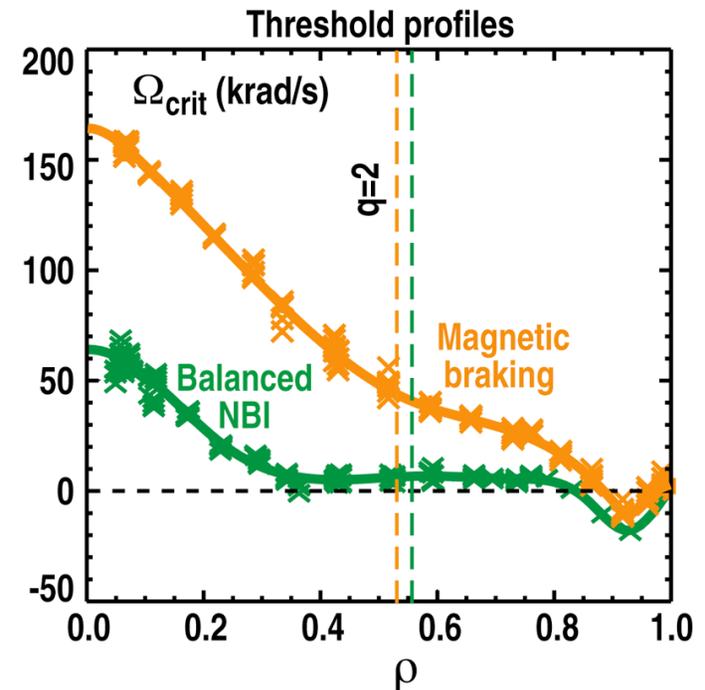


Much Slower Rotation Before RWM Onset is Observed by Reducing the Injected Torque With Minimized Error Fields

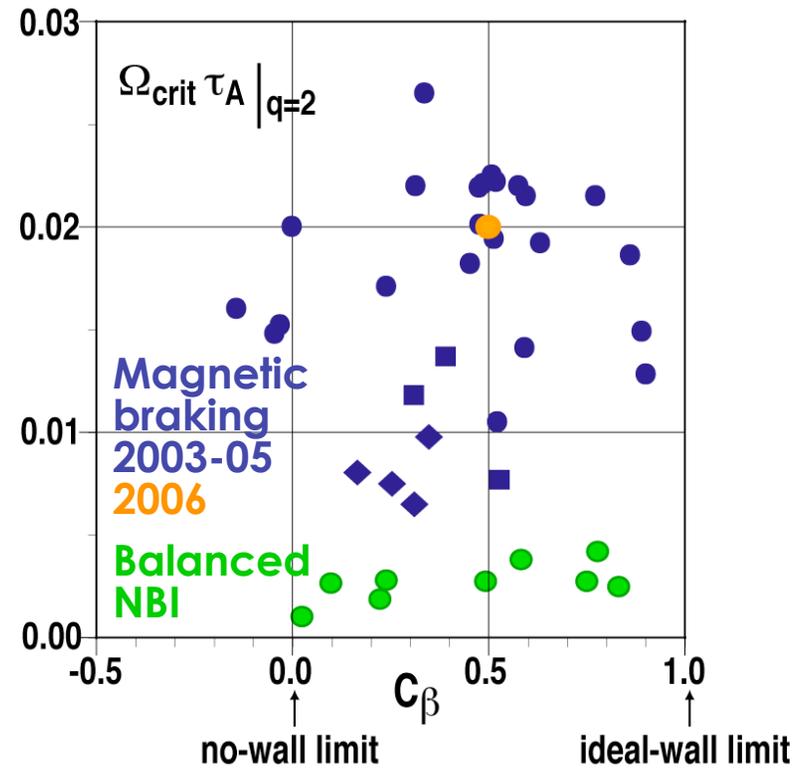
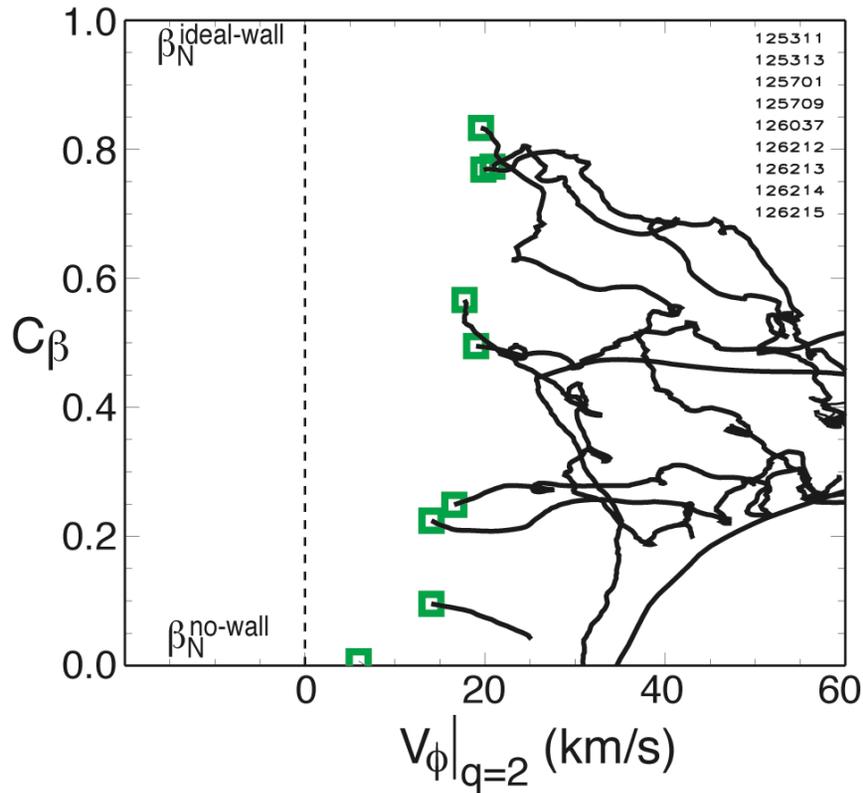
- DIII-D using a varying mix of co and counter NBI:



- Plasma rotation is reduced uniformly for $\rho < 0.9$
- Ω_{crit} at $q = 2$ is $\sim 10x$ slower than measured with magnetic braking

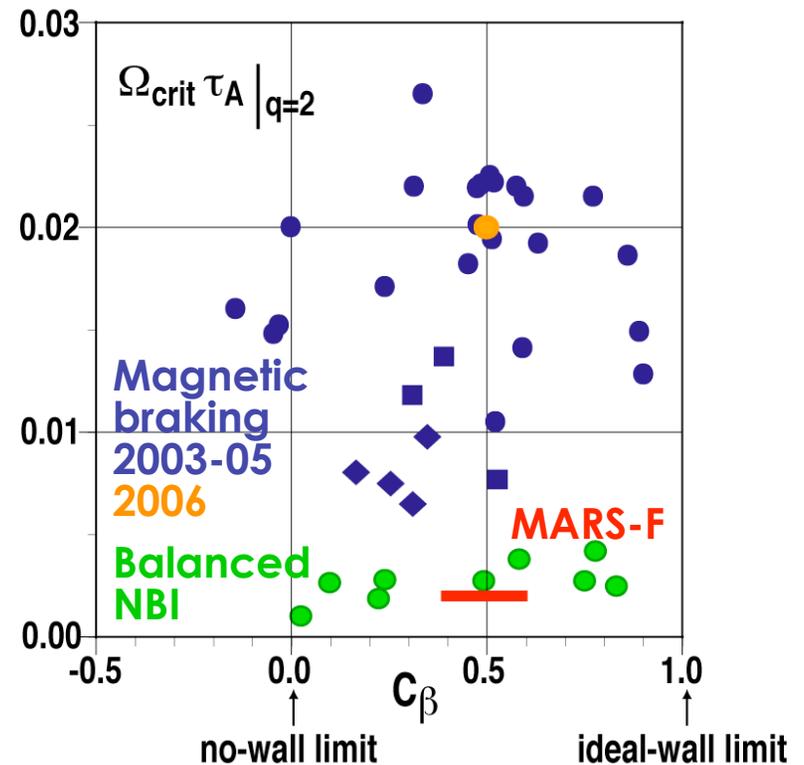
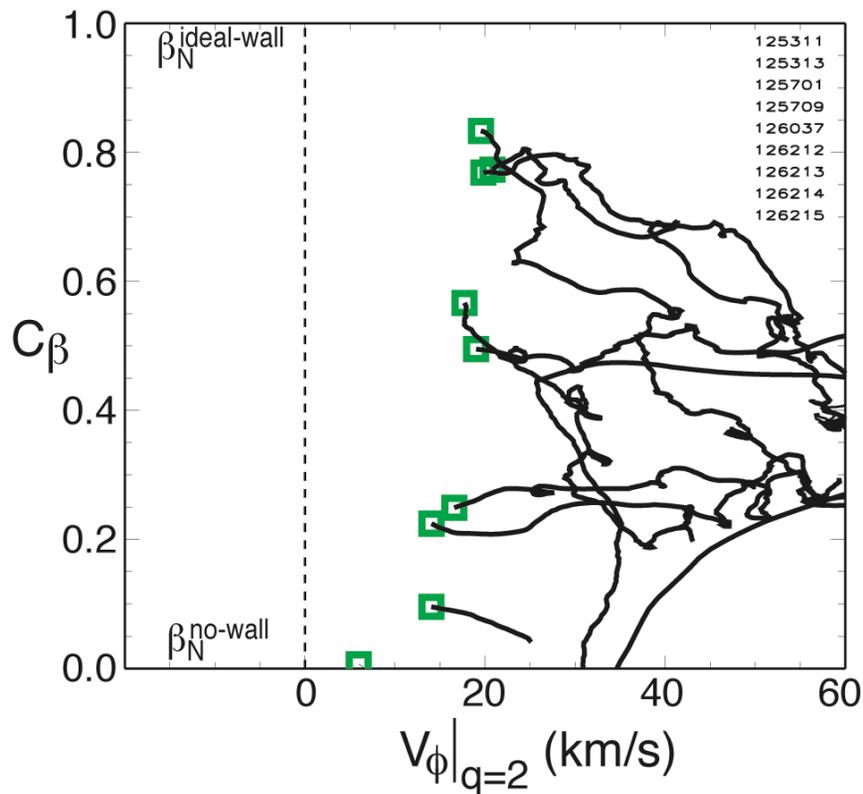


Weak β -Dependence is Observed for Rotation Thresholds Measured With Minimized Error Fields



- RWM onset (\square) observed when V_ϕ at $q=2$ is $\sim 10\text{-}20$ km/s, or $\sim 0.3\%$ of local V_A

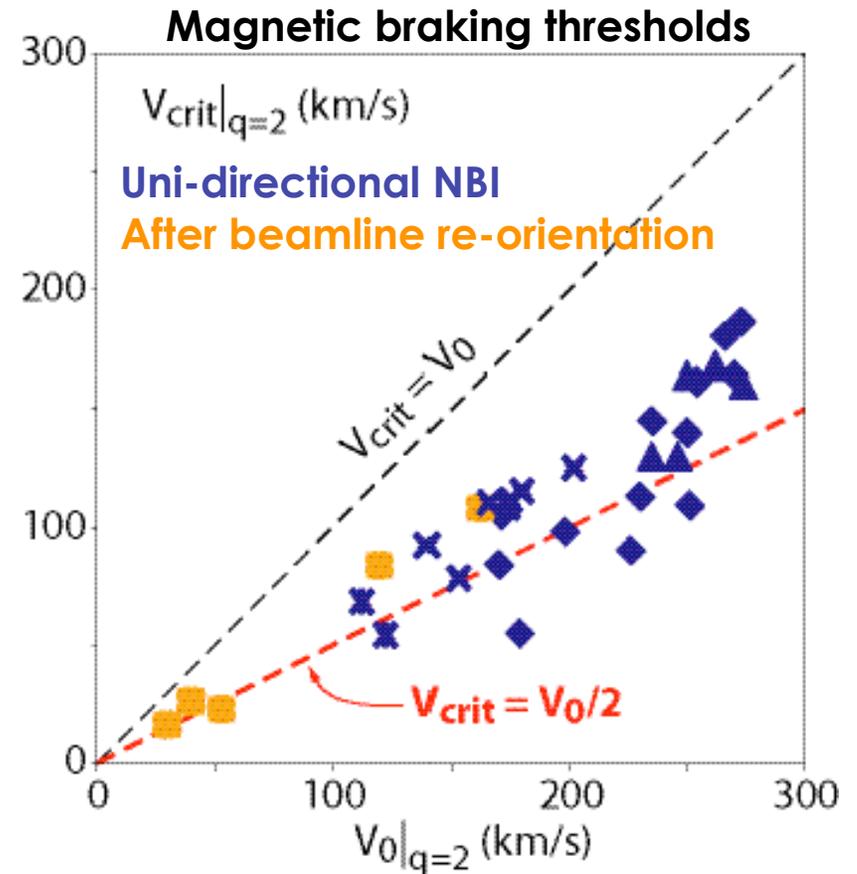
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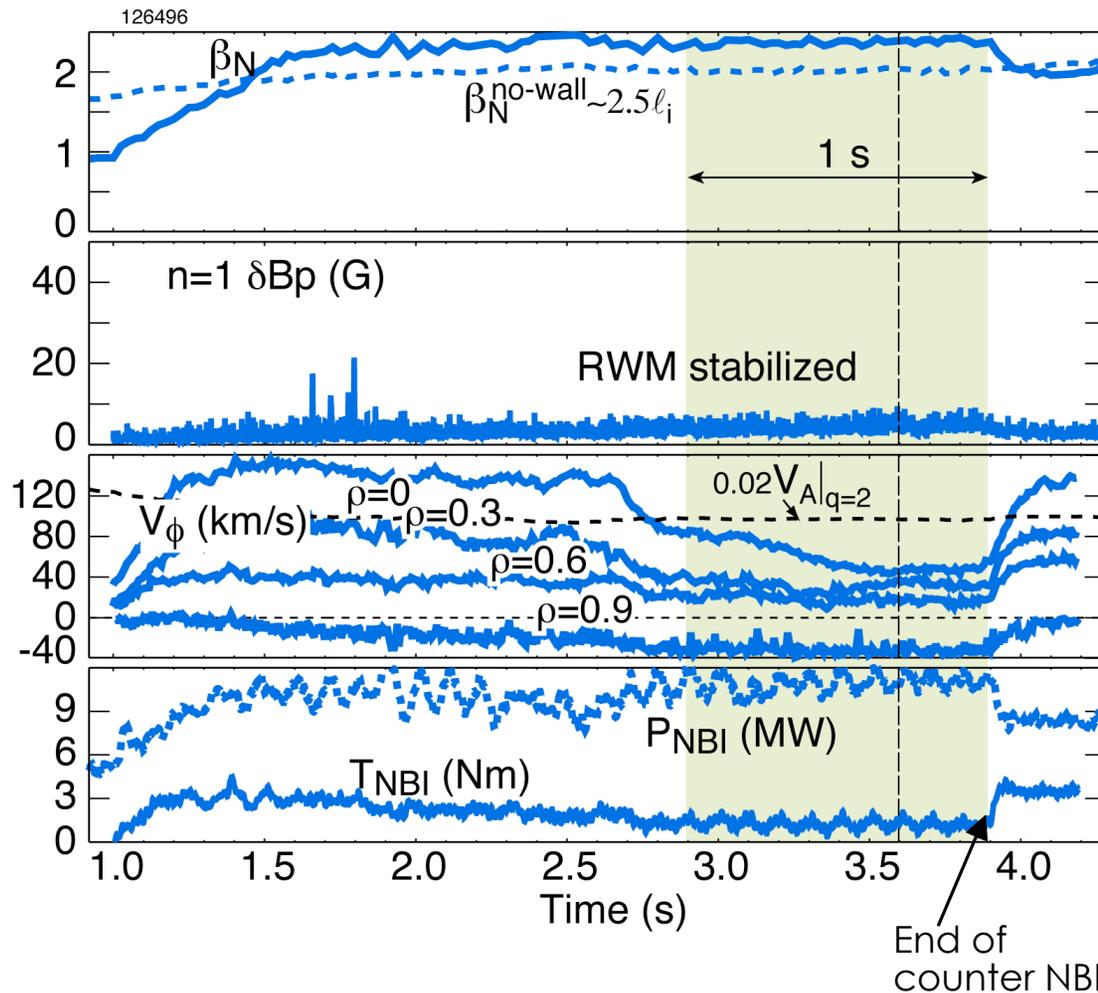
- RWM onset (\square) observed when V_ϕ at $q=2$ is ~ 10 - 20 km/s, or $\sim 0.3\%$ of local V_A
- Ideal MHD with dissipation implemented in MARS-F (kinetic damping model [Bondeson and Chu]) predicts slow rotation threshold for balanced NBI plasmas

High Threshold Measured With Magnetic Braking May Correspond to Entrance Into Forbidden Band of Rotation

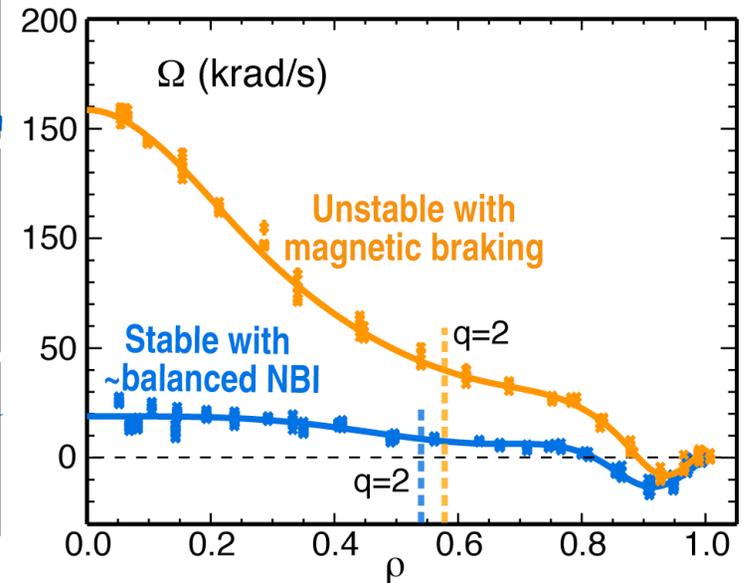
- **Increasing static non-axisymmetric field leads to bifurcation in torque-balance equilibrium of plasma**
 - Rotation must jump from a high value to essentially locked
- **“Induction motor” model of error field-driven reconnection [Fitzpatrick]:**
 - Plasma rotation at critical point, $V_{\text{crit}} \sim 1/2$ of unperturbed rotation, V_0
- **Lower neutral beam torque gives lower V_0 , therefore a lower V_{crit} at entrance to forbidden band of rotation**



With Optimal Error Field Correction, RWM Stabilization at Very Slow Plasma Rotation Sustained for >300 Wall Times

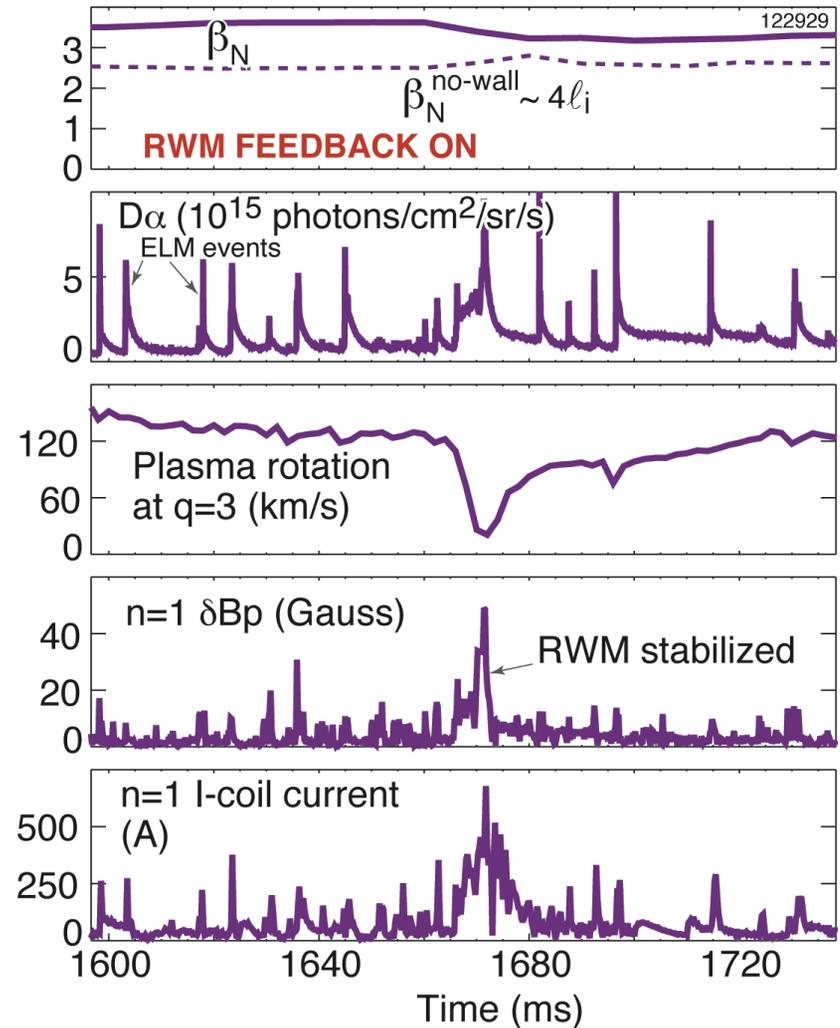
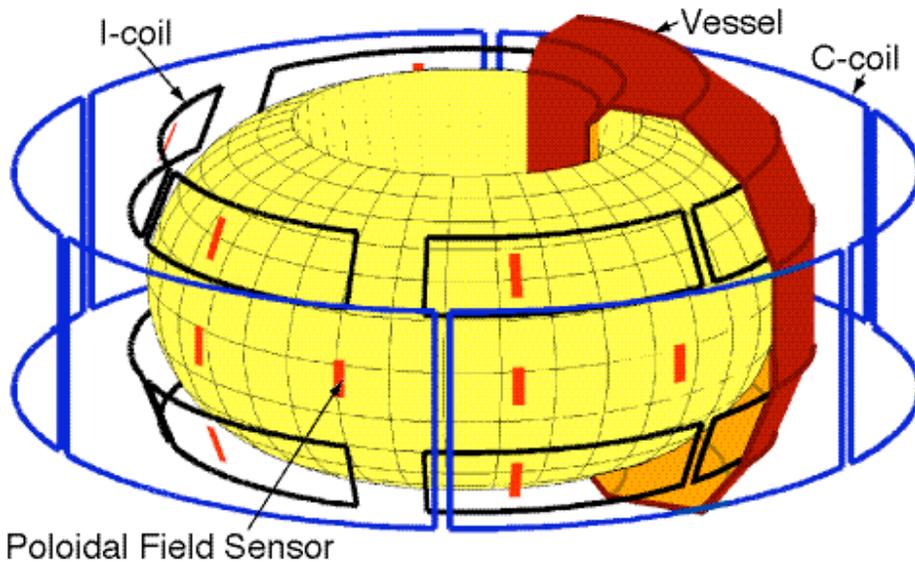


- Plasma rotation just above $\Omega_{\text{crit}} \sim 0.35\% \Omega_A$ at $q=2$ is sufficient to sustain β_N , above no-wall limit



In High Performance Plasmas, Active RWM Feedback May Still be Required

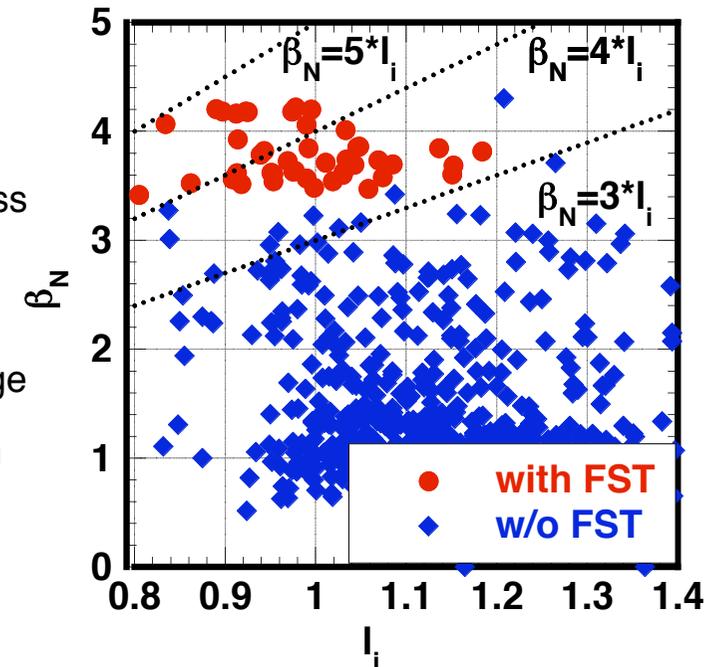
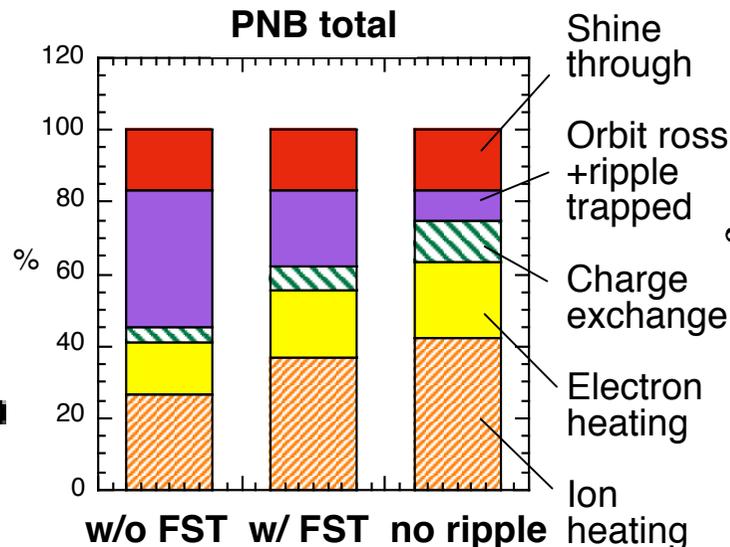
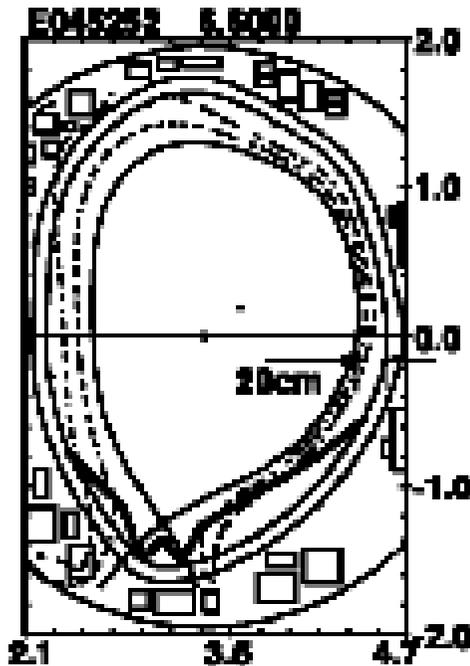
- In DIII-D, large, slow-varying $n=1$ currents in external coils provide error field correction, maintain high rotation
- Large ELMs can lead to loss of rotational stabilization
- Smaller, faster-varying $n=1$ currents in internal coils can respond to transient events, maintaining RWM stabilization



Ferritic Steel Tiles (FST) lead to high beta on large JT-60U plasmas

JT-60U

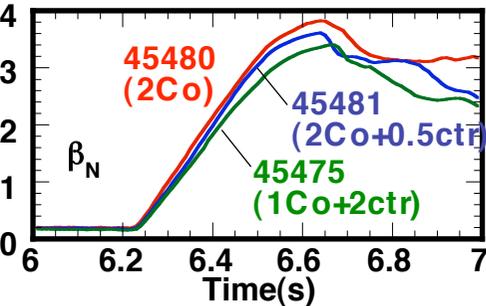
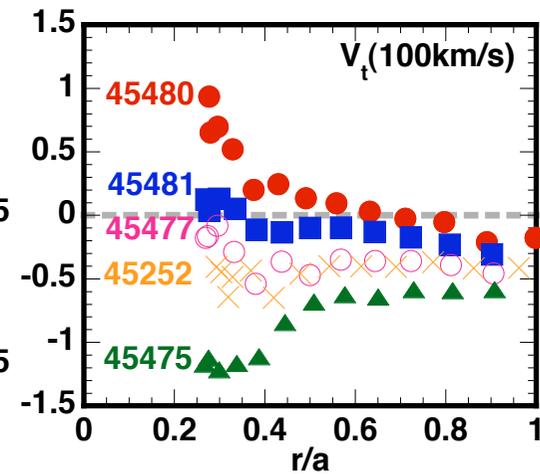
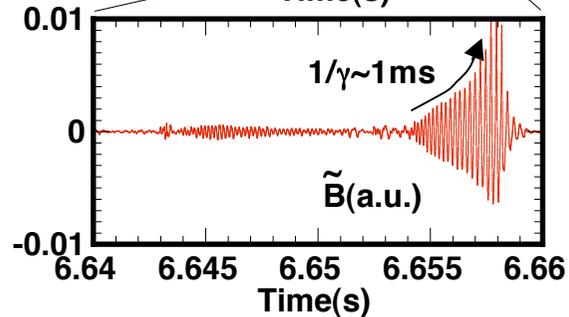
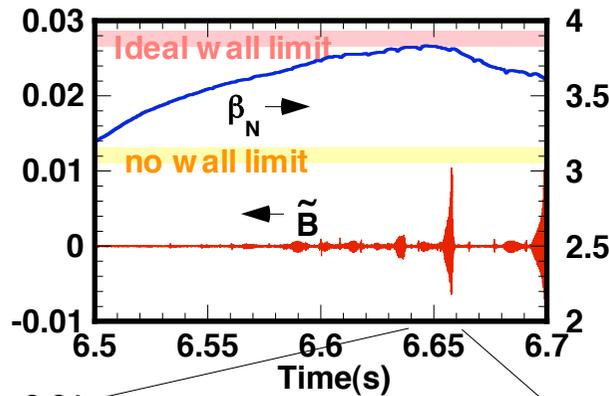
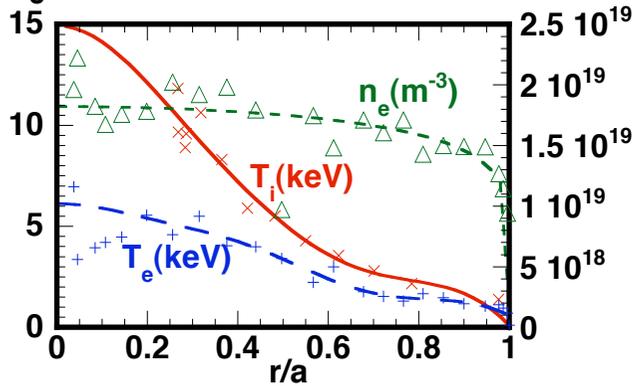
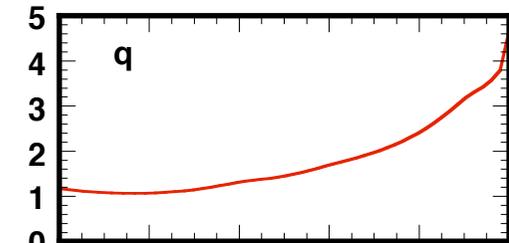
- **Before installing ferritic steel tiles**, few large plasmas reached the ideal beta limit, however it is difficult to exceed it due to lack of NB power.
- The net NB power with FST is 1.34 times larger than that w/o FST due to reduction of ripple loss.
- Increase net power of ~ 3.5 MW corresponding to 2 tangential beams.
 - --> Change rotation by one-way tangential NB injection.
- Achieved high $\beta_N \sim 4.2$ exceeding ideal limit at $I_i < 1.2$ and $V_p > 70 \text{ m}^3$ ($\beta_N \sim 3.4$ w/o FST).



β_N is restricted by the MHD instability

JT-60U

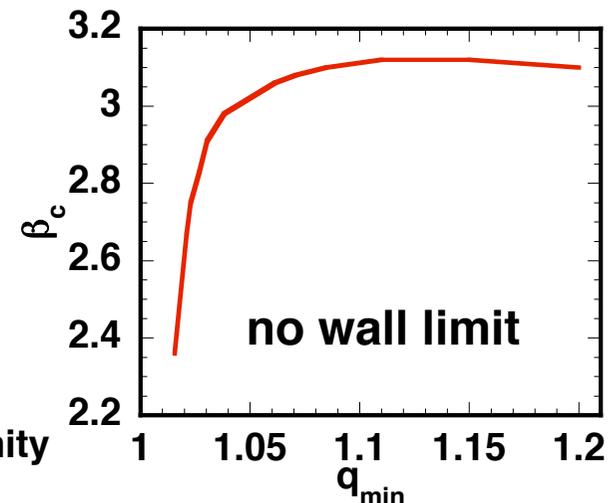
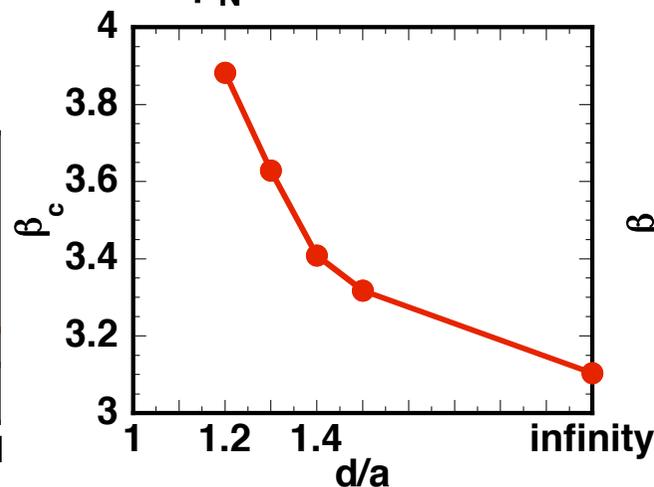
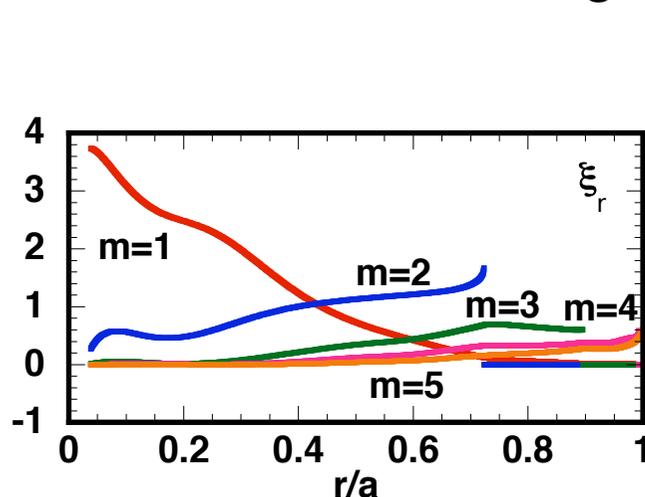
- $B_t=1.575$, $I_p=0.9\text{MA}$, $q_{\min}\sim 1.1$, $q_{95}\sim 3.5$, $d/a\sim 1.2$
- High β_p -H mode plasma (ITB&ETB)
- The $n=1$ ($m\sim 3$) mode appears at high beta region.
- The mode grows with growth time $1/\gamma\sim 1\text{ms}$ before collapse.
- Frequency of the mode is $\sim 1\text{-}5\text{ kHz}$
- Highest beta is obtained with co-rotation
- Confinement is best for the co-rotation plasma



β_N is determined by the ideal wall limit. (MARG2D code)

JT-60U

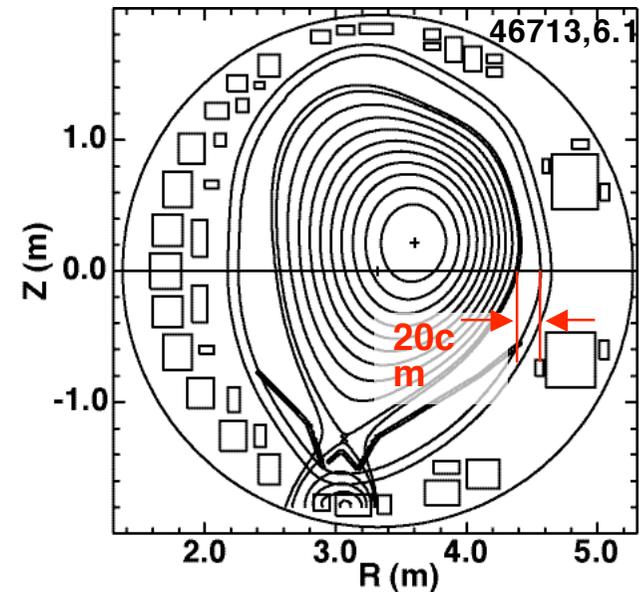
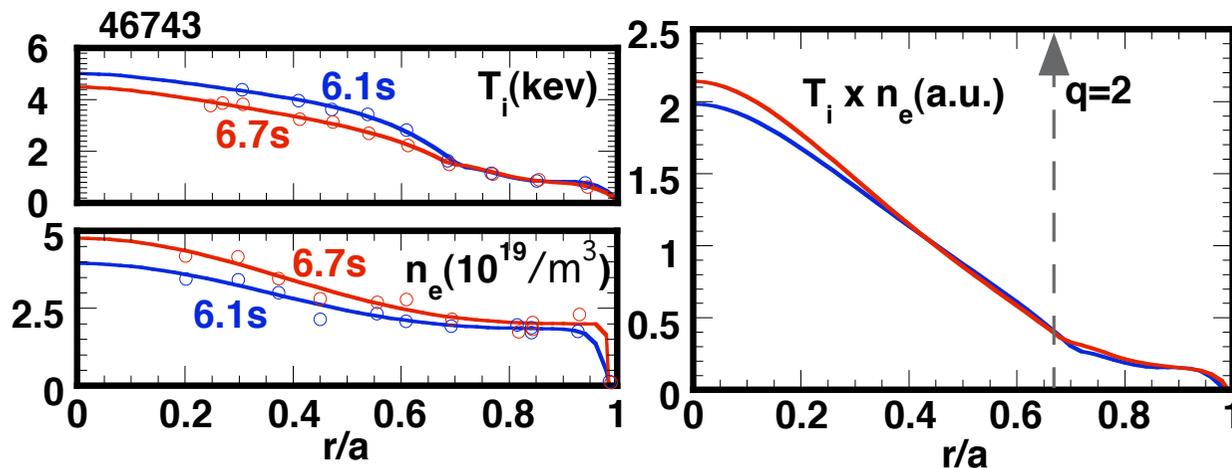
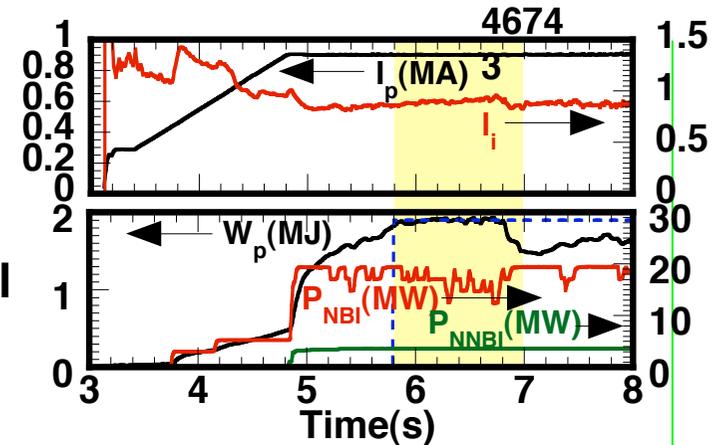
- The dominant poloidal component is $m=1$ due to strong ITB at $r/a \sim 0.2$.
- The mode is stabilized by the wall and ideal wall limit is $\beta_N \sim 3.9$ for the plasma at $d/a=1.2$ when no wall limit is $\beta_N \sim 3.1$.
 - > Beta reaches ideal wall limit
- Current profile is determined by competition between current diffusion and increasing bootstrap current
- Small $q_{\min} (\sim 1.0)$ for small and ctr rotation plasmas due to small bootstrap current.
 - > Critical beta decrease at $q_{\min} < 1.1$. ($q_{\min} \sim 1.08$ at highest beta plasma).
 - > Small ideal wall limit.
- The critical beta is affected by the peripheral plasma current.
 - > Small current ramp down before NB injection to reduce edge current.
 - > Achieved highest beta $\beta_N \sim 4.2$.



RWM experiment for critical rotation

JT-60U

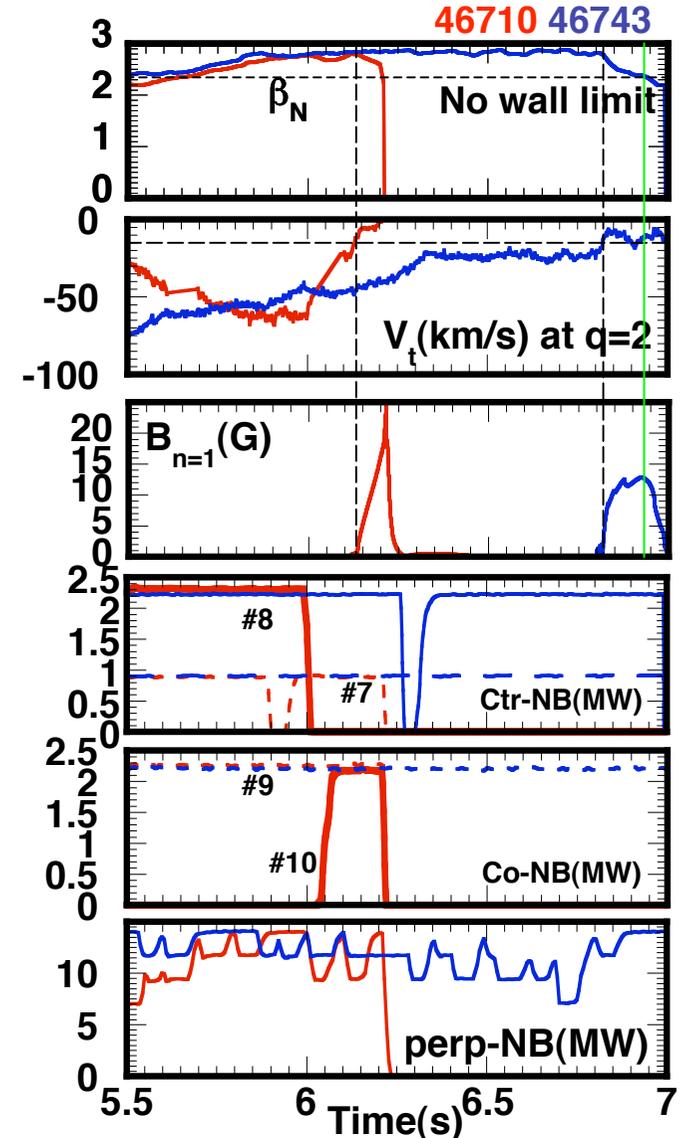
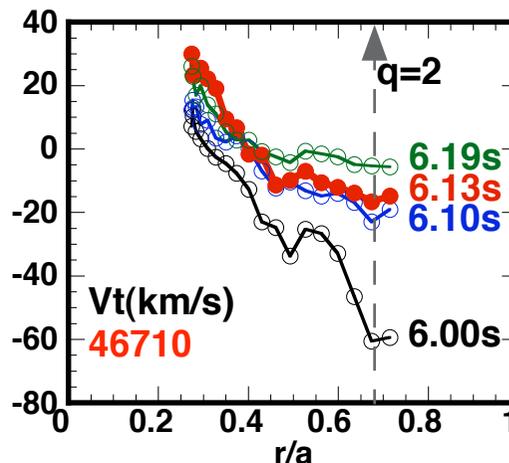
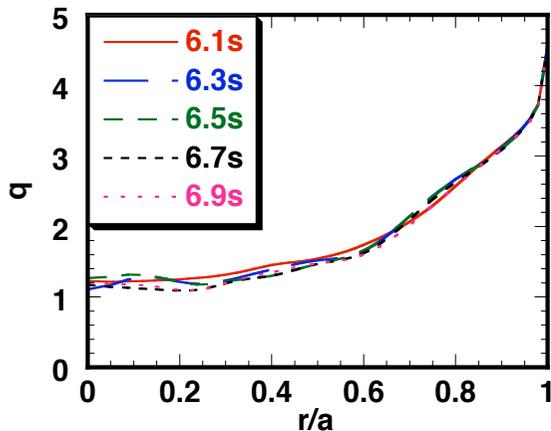
- $B_t=1.575$ T, $I_p=0.9$ MA, $q_{min}\sim 1.2$, $q_{95}\sim 3.5$
- $d/a\sim 1.2$
- To increase q_{min} , pre-NB is injected during current ramp up
- β_N is kept constant and change the tangential NB from ctr-NB to co-NB.
- Pressure and current profile is also kept constant



RWM is suppressed by plasma rotation

JT-60U

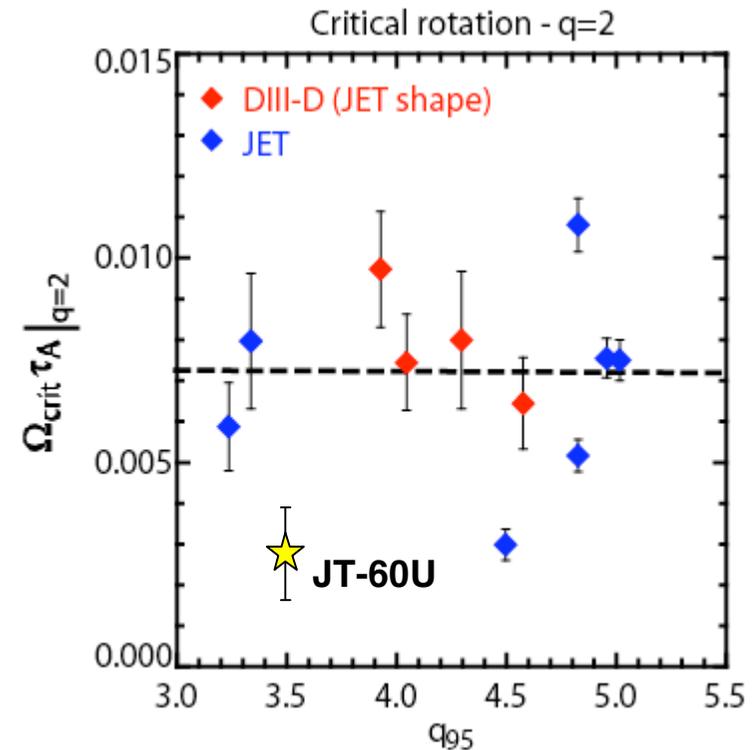
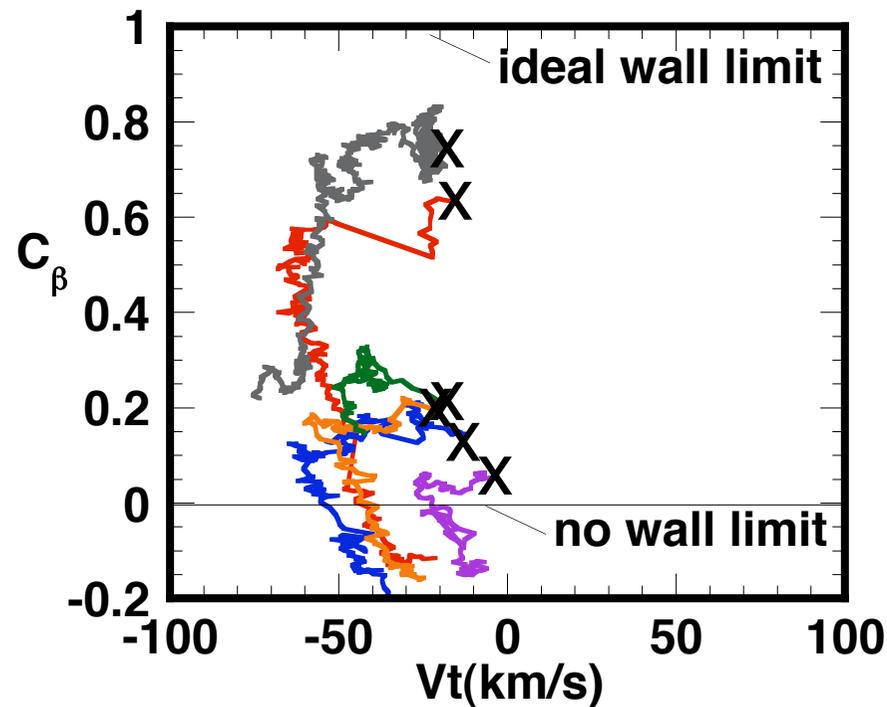
- β_N is kept constant and change the tangential NB from ctr-NB to co-NB.
- Rotation can be controlled by changing tangential NB combination
- Disruption or collapse occurs at $V_t \sim 10$ km/s $\rightarrow n=1$ mode grow with $1/\gamma \sim 10$ ms .
- The mode suppressed after $\beta_N < \beta_{N \text{ no-wall limit}}$
- To investigate the effect of beta on critical rotation, we change the constant β_N .



Critical Rotation

JT-60U

- Critical rotation $V_c \sim 5\text{-}20\text{km/s}$
- $V_c/V_A \sim 0.3\%$ ($q_{95} \sim 3.5$) is much smaller than previous DIII-D and JET results using magnetic braking
 - Indicating importance of error field?
- V_c does not increase as C_β increase

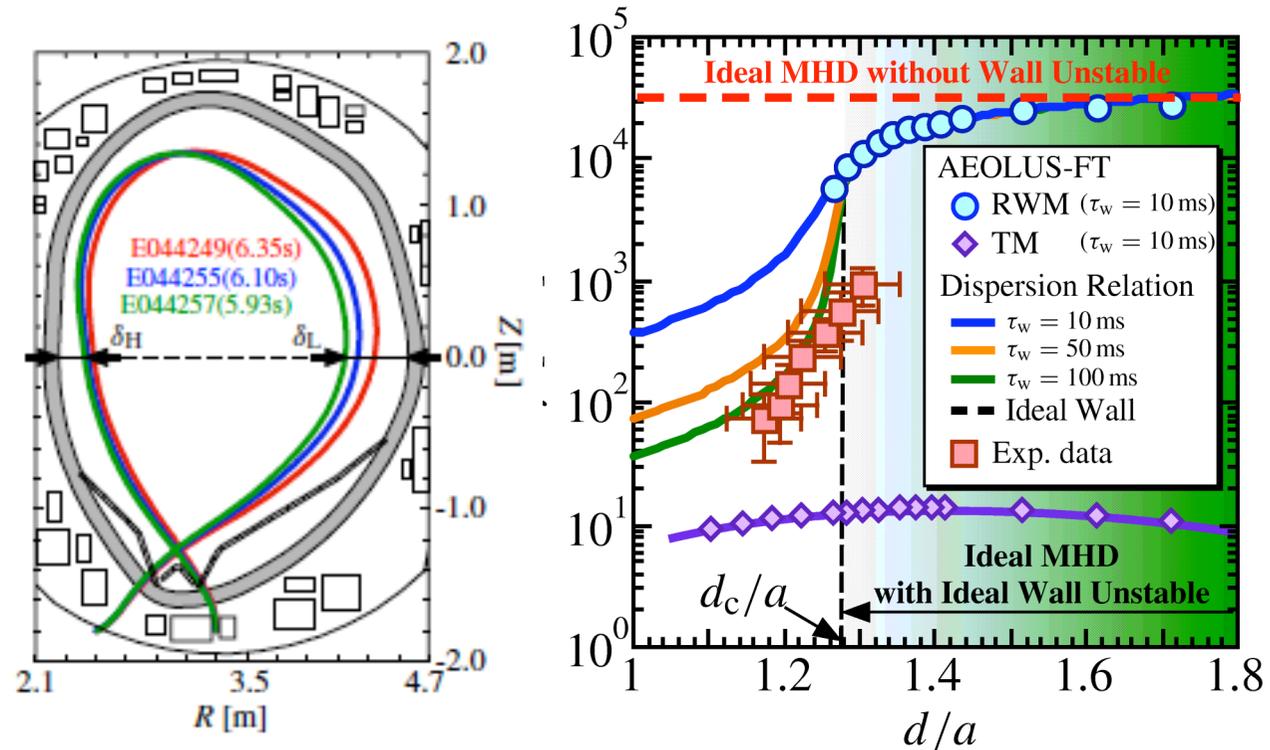


Current driven RWM experiment for wall effect

JT-60U

Experimentally obtained growth rates are consistent with RWM, wall stabilization effects were observed

- AEOLUS-FT, which can take into account the resistivity of the wall, found 3/1 kink and 2/1 tearing branches.
- The above dispersion with no plasma rotation and no dissipation is consistent with AEOLUS-FT.
- These modes have been observed in the region where the ideal MHD mode with ideal wall is stable.
- From the strong dependence, the observed modes can be identified as RWM.



New Hardware Capabilities Allow Simultaneous Discovery of Low RWM Rotation Threshold in DIII-D and JT-60U

- **The plasma rotation needed for RWM stabilization is much slower than previously thought**
 - Achieved with neutral beam line re-orientation in DIII-D:
 - Balanced neutral beam injection -> lower injected torque and plasma rotation with minimized non-axisymmetric fields
 - Achieved with ferritic steel tiles in JT-60U:
 - Reduced ripple loss -> higher confinement and β with smaller plasma-wall separation
 - Such a slow rotation should be achievable in ITER
- **Ideal MHD with dissipation (MARS-F with kinetic model) in agreement with new low threshold rotation for RWM stabilization**
- **Even with sufficient rotation, active feedback may still be needed, but system requirements could be reduced**
- **RWM stabilization allows demonstration of high performance tokamak regimes ($\beta_N > 4$)**

